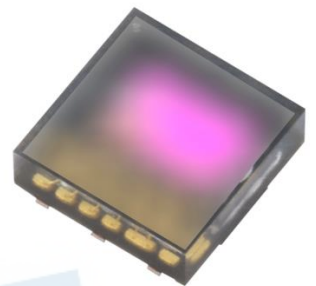


### Ambient Light Sensor with I<sup>2</sup>C Interface ALS-DPDIC17-78C/L749/TR8

#### Features

- 10~16bit ADC resolution
- Specially coated photo diode with an optical response similar to human eyes
- High resolution (0.0033Lux/count)
- 50Hz/60Hz flicker noise and IR rejection
- Amplifier with adjustable gain (x1, x4, x8, x32, X96)
- Individual programmable low and high threshold for interrupt function
- Programmable integration time
- The product itself will remain within RoHS compliant version
- Compliance with EU REACH
- Compliance Halogen Free(Br < 900ppm, Cl < 900ppm, Br+Cl < 1500ppm)



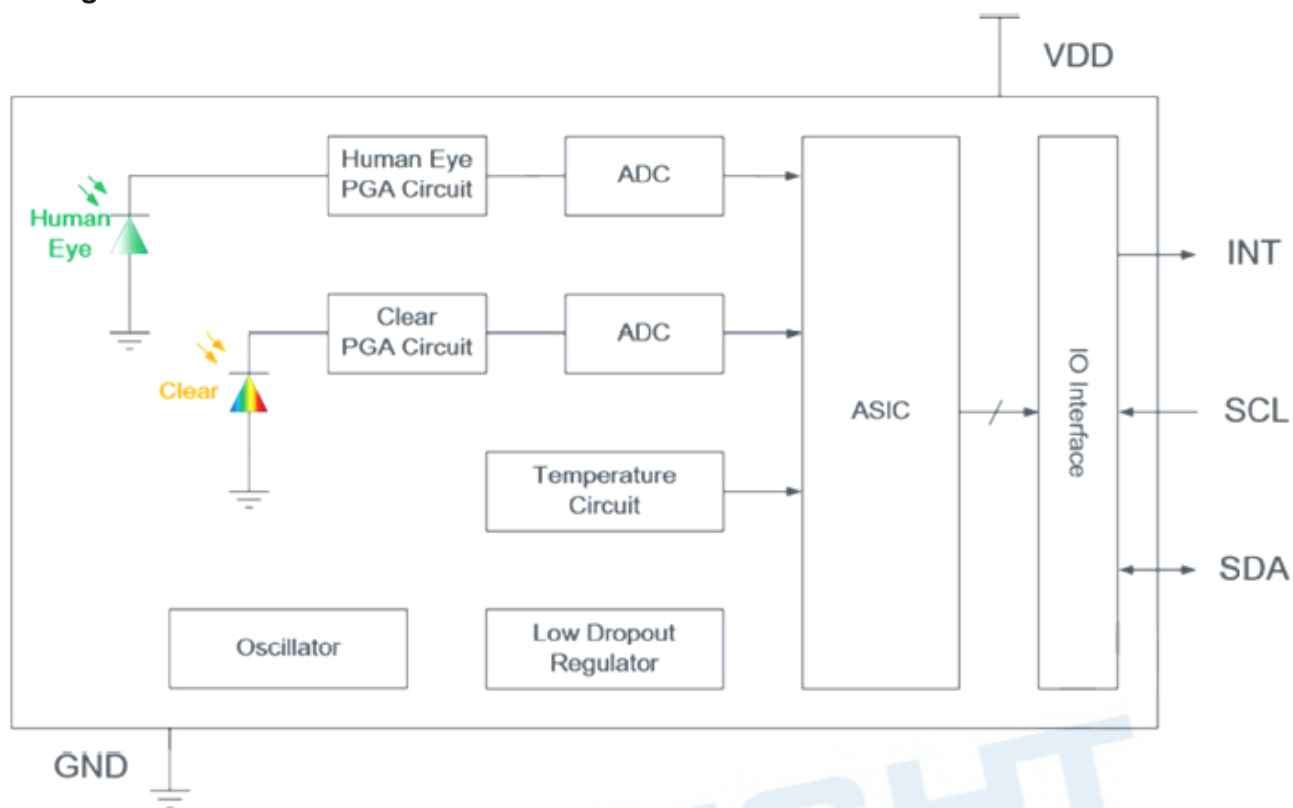
#### Description

The ALS-DPDIC17-78C/L749/TR8 is a digital output ambient light with I<sup>2</sup>C interface and interrupt. It has a flexible and wide operating range for the ambient light sensor with a maximum resolution of 0.0033Lux/count and a maximum detectable illumination of 83000Lux. The ALS-DPDIC17-78C/L749/TR8 built-in an optical filter for IR rejection, and providing a spectrum which is close to the human eye's response. Dual-channel output (human eye and clear), so it has excellent light ratio under different light conditions.

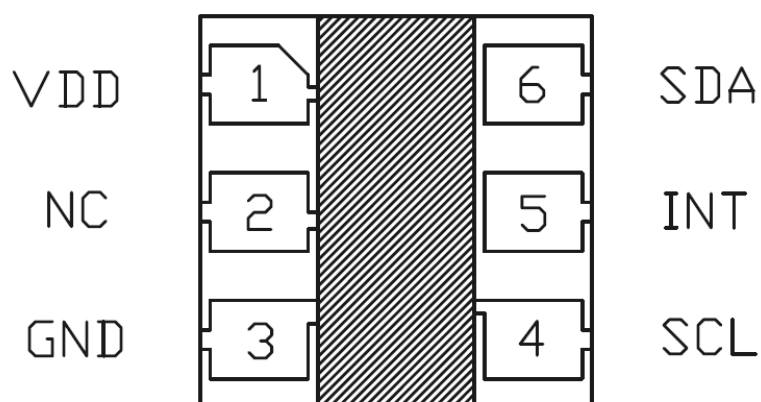
#### Applications

- Detection of ambient for controlling the backlight of TFT LCD display.
- Automatic residential and commercial lighting management.
- Automatic contrast enhancement for electronic signboard.
- Mobile phone, Smart phone, PDA, Tablet PC.

## Block Diagram



## I/O Pins Configuration



Top View

## Pad Description

| Pin | I/O Type | Pin Name | Description                        |
|-----|----------|----------|------------------------------------|
| 1   | PWR      | VDD      | Power supply                       |
| 2   | NC       | NC       | No connection                      |
| 3   | GND      | GND      | Ground                             |
| 4   | I        | SCL      | I <sup>2</sup> C serial clock line |
| 5   | O        | INT      | Interrupt pin                      |
| 6   | I/O      | SDA      | I <sup>2</sup> C serial data line  |

Direction denotation:

| I/O Type | Dir.   | I/O Type | Dir.           |
|----------|--------|----------|----------------|
| O        | Output | GND      | Ground         |
| I        | Input  | I/O      | Input / Output |
| PWR      | Power  | NC       | Not Connect    |

## Absolute Maximum Ratings

| Parameter                        | Symbol           | Rating      | Unit |
|----------------------------------|------------------|-------------|------|
| Supply Voltage                   | V <sub>DD</sub>  | 4.5         | V    |
| I <sup>2</sup> C Bus Pin Voltage | SCL, SDA, INT    | -0.2 to 4.5 | V    |
| I <sup>2</sup> C Bus Pin Current | SCL, SDA, INT    | 10          | mA   |
| Operating Temperature            | T <sub>ope</sub> | -40 to +85  | °C   |
| Storage Temperature              | T <sub>stg</sub> | -45 ~ 100   | °C   |
| ESD Rating                       | Human Body Model | 2           | KV   |

Note:

Exceeding these ratings could cause damage to the device. All voltages are with respect to ground. Currents are positive into,

negative out of the specified terminal.

## Recommended Operating Conditions

| Parameter                                                | Symbol              | Min. | Typ. | Max.            | Unit | Condition                          |
|----------------------------------------------------------|---------------------|------|------|-----------------|------|------------------------------------|
| Supply Voltage <sup>Note1</sup>                          | V <sub>DD</sub>     | 2.4  | -    | 3.6             | V    | -                                  |
| I <sup>2</sup> C Bus Pin Voltage                         | V <sub>Bus</sub>    | 1.62 | 1.8  | V <sub>DD</sub> | V    | V <sub>Bus</sub> ≤ V <sub>DD</sub> |
| Operating Temperature                                    | T <sub>ope</sub>    | -40  | -    | +85             | °C   | -                                  |
| I <sup>2</sup> C Bus Input High Voltage <sup>Note2</sup> | V <sub>IH_SCL</sub> | 1.4  | -    | -               | V    | -                                  |
|                                                          | V <sub>IH_SDA</sub> | -    | -    | -               | V    | -                                  |
| I <sup>2</sup> C Bus Input Low Voltage <sup>Note2</sup>  | V <sub>IL_SCL</sub> | -    | -    | 0.5             | V    | -                                  |
|                                                          | V <sub>IL_SDA</sub> | -    | -    | 0.5             | V    | -                                  |
| SDA Output Low Voltage                                   | V <sub>OL_SDA</sub> | 0    | -    | 0.4             | V    | 3mA sinking current                |
| INT Output Low Voltage                                   | V <sub>OL_INT</sub> | 0    | -    | 0.4             | V    | 3mA sinking current                |

Notes:

1. The power supply need to make sure the V<sub>DD</sub> slew rate at least 1.0V/ms. ALS-DPDIC17-78C/L749/TR8 have power on reset function. When V<sub>DD</sub> drops below 2V under room temp, the IC will be reset automatically. Then power back up at the requirement slew rate, and write registers to the desired values.

2. The specs are defined under V<sub>DD</sub>=3.3V, T<sub>a</sub>=25°C

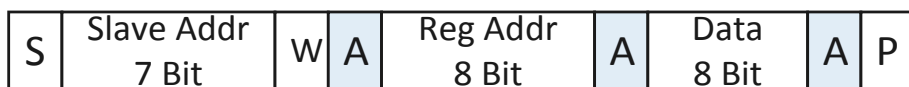
## Electro-Optical Characteristics

| Parameter                       | Symbol            | Min. | Typ. | Max.   | Unit     | Condition                                                        |
|---------------------------------|-------------------|------|------|--------|----------|------------------------------------------------------------------|
| Active Supply Current           | I <sub>DD</sub>   | -    | 160  | 300    | μA       | E <sub>v</sub> =0 lx<br>Note1                                    |
|                                 | I <sub>PD</sub>   | -    | 2.5  | -      | μA       | Sleep mode<br>E <sub>v</sub> = 0 lx<br>I <sup>2</sup> C inactive |
| <b>Ambient Light Sensor</b>     |                   |      |      |        |          |                                                                  |
| ALS A/DC resolution             | -                 | 10   | -    | 16     | bit      | -                                                                |
| Number of ADC integration time  | ATIME             | 1    | -    | 256    | step     | -                                                                |
| ALS Dark Output                 | CH0               | 0    | 1    | 5      | counts   | E <sub>v</sub> =0 lx, ALS gain=x96,<br>Tint =674ms               |
|                                 | CH1               | 0    | 1    | 5      |          |                                                                  |
| ALS detection output            | CH0               | 1610 | 2300 | 2990   | counts   | E <sub>v</sub> =100 lx, ALS gain=x32,<br>Tint =170ms             |
|                                 | CH1               | 2170 | 3100 | 4030   |          |                                                                  |
| ALS detection resolution        | -                 | -    | -    | 0.0033 | lx/count | ALS gain=x96,Tint=674ms                                          |
| ALS maximum detection           | -                 | -    | -    | 83K    | Lux      | ALS gain=x1,Tint=5.5ms                                           |
| ALS sensitivity peak wavelength | λ <sub>PALS</sub> | -    | 550  | -      | nm       | For channel 0                                                    |

Note :

1. V<sub>DD</sub> = 3.3 V, T<sub>a</sub> = 25°C, **EN\_ALS=1, ALSCONV=0x3F, PGA\_ALS =0x04, WTIME=0x07**

### I2C Write Format



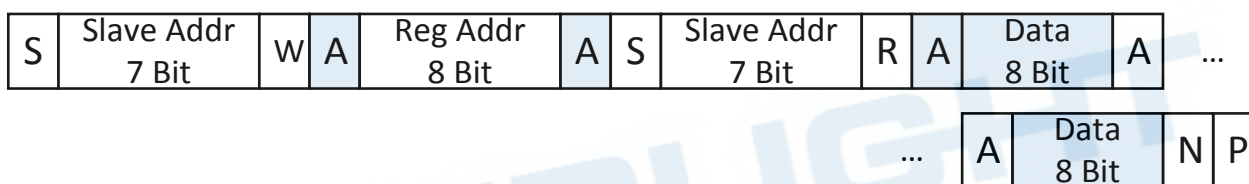
### I2C Block Write Format



### I2C Read Format



### I2C Block Read Format



|                          |                 |                          |   |                                     |
|--------------------------|-----------------|--------------------------|---|-------------------------------------|
| <input type="checkbox"/> | Master to Slave | <input type="checkbox"/> | S | Start Condition, 1 Bit              |
| <input type="checkbox"/> | Slave to Master | <input type="checkbox"/> | P | Stop Condition, 1 Bit               |
|                          |                 | <input type="checkbox"/> | W | Write, Set 0 for write, 1 Bit       |
|                          |                 | <input type="checkbox"/> | R | Read, Set 1 for read, 1 Bit         |
|                          |                 | <input type="checkbox"/> | A | Acknowledge(ACK), Set 0, 1 Bit      |
|                          |                 | <input type="checkbox"/> | N | Non acknowledge(NACK), Set 1, 1 Bit |

### I2C Slave Address and R/W bit

This address is seven bits long followed by an eighth bit which is a data direction bit (R/W). A '0' indicates a transmission (WRITE), a '1' indicates a request for data (READ). The slave address of this device is 0x38.

## Register Set

The ALS-DPDIC17-78C/L749/TR8 is operated over the I<sup>2</sup>C bus with registers that contain configuration, status, and result information. All registers are 8 bits long.

| Address | Name         | Type | Default value | Description                                                |
|---------|--------------|------|---------------|------------------------------------------------------------|
| 0x00    | SYSM_CTRL    | RW   | 0x00          | ALS operation mode control, waiting mode control, SW reset |
| 0x01    | INT_CTRL     | RW   | 0x03          | Interrupt pin control, interrupt persist control           |
| 0x02    | INT_FLAG     | RW   | 0x00          | Interrupt flag, error flag, power on reset(POR) flag       |
| 0x03    | WAIT_TIME    | RW   | 0x00          | Waiting time setting                                       |
| 0x04    | ALS_GAIN     | RW   | 0x00          | ALS analog gain setting                                    |
| 0x05    | ALS_TIME     | RW   | 0x00          | ALS integrated time setting                                |
| 0x0B    | PERSISTENCE  | RW   | 0x11          | ALS persistence setting                                    |
| 0x0C    | ALS_THRES_LL | RW   | 0x00          | ALS lower interrupt threshold - LSB                        |
| 0x0D    | ALS_THRES_LH | RW   | 0x00          | ALS lower interrupt threshold - MSB                        |
| 0x0E    | ALS_THRES_HL | RW   | 0xFF          | ALS higher interrupt threshold - LSB                       |
| 0x0F    | ALS_THRES_HH | RW   | 0xFF          | ALS higher interrupt threshold - MSB                       |
| 0x16    | INT_SOURCE   | RW   | 0x00          | ALS interrupt source                                       |
| 0x17    | ERROR_FLAG   | RW   | 0x00          | Error flag                                                 |
| 0x1C    | CH0_DATA_L   | R    | 0x00          | Channel 0 output data - LSB                                |
| 0x1D    | CH0_DATA_H   | R    | 0x00          | Channel 0 output data - MSB                                |
| 0x1E    | CH1_DATA_L   | R    | 0x00          | Channel 1 output data - LSB                                |
| 0x1F    | CH1_DATA_H   | R    | 0x00          | Channel 1 output data - MSB                                |
| 0xBC    | PNO_LB       | R    | 0x14          | Product number, Low Byte                                   |
| 0xBD    | PNO_HB       | R    | 0x16          | Product number, High Byte                                  |

## SYSM\_CTRL

| 0x00 | SYSM_CTRL, System Control (Default = 0x00) |         |   |   |   |   |   |        |
|------|--------------------------------------------|---------|---|---|---|---|---|--------|
| BIT  | 7                                          | 6       | 5 | 4 | 3 | 2 | 1 | 0      |
| R/W  | SWRST                                      | EN_WAIT | 0 | 0 | 0 | 0 | 0 | EN_ALS |

**SWRST** : Software reset. Reset all register to default value.

0: (default)

1: Reset will be triggered.

**EN\_WAIT** : Waiting time will be inserted between two measurements.

0: Disable waiting function.

1: Enable waiting function.

**EN\_ALS** : Enables ALS function.

0: Disable ALS function (default)

1: Enable ALS function

## INT\_CTRL

| 0x01 | Interrupt Pin Control (Default = 0x03) |   |   |          |   |   |   |         |
|------|----------------------------------------|---|---|----------|---|---|---|---------|
| BIT  | 7                                      | 6 | 5 | 4        | 3 | 2 | 1 | 0       |
| R/W  | 0                                      | 0 | 0 | ALS_SYNC | 0 | 0 | 0 | EN_AINT |

**ALS\_SYNC** : Measurement is pended when ALS interrupt is triggered. Until clear the interrupt then start the next measurement.

0: Disable pending ALS function (default).

1: Enable pending ALS function.

**EN\_AINT** : The ALS interrupt (INT\_ALS) flag can trigger the INT pin to low.

0: Disable **INT\_ALS** effect INT pin.

1: Enable **INT\_ALS** effect INT pin (default)

## INT\_FLAG

| 0x02 | INT_FLAG, System Control (Default = 0x00) |           |   |   |   |   |   |         |
|------|-------------------------------------------|-----------|---|---|---|---|---|---------|
| BIT  | 7                                         | 6         | 5 | 4 | 3 | 2 | 1 | 0       |
| R/W  | INT_POR                                   | DATA_FLAG | 0 | 0 | 0 | 0 | 0 | INT_ALS |

**INT\_POR** : Power-On-Reset Interrupt flag trigger the INT pin when the flag sets to one.

0: Write zero to clear the flag.

1: This bit will be set to one when it satisfy one of the following conditions:

- Power On
- VDD < 2.0V
- SWRST

**DATA\_FLAG** : It shows if any data is invalid after completion of each conversion cycle. This bit is read-only.

0: data valid

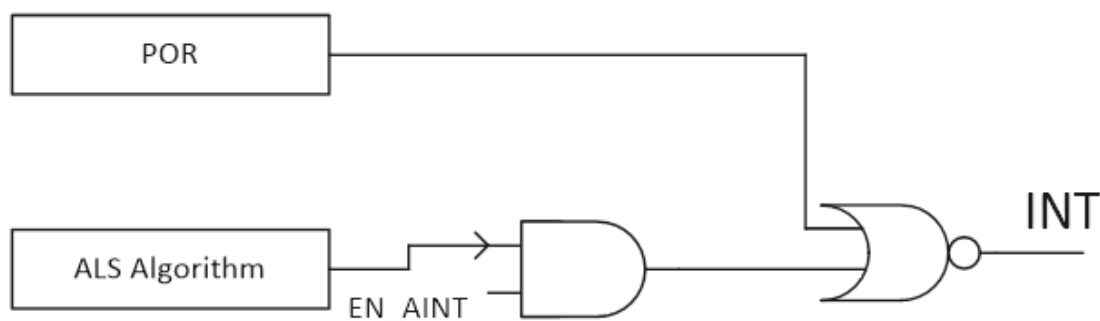
1: data invalid

**INT\_ALS** : ALS Interrupt flag. It correlation with CH0/1 data and ALS high/low threshold. Write zero to clear the flag.

0: ALS Interrupt not trigger or be cleared.

1: ALS Interrupt triggered

## Interrupt Behavior :



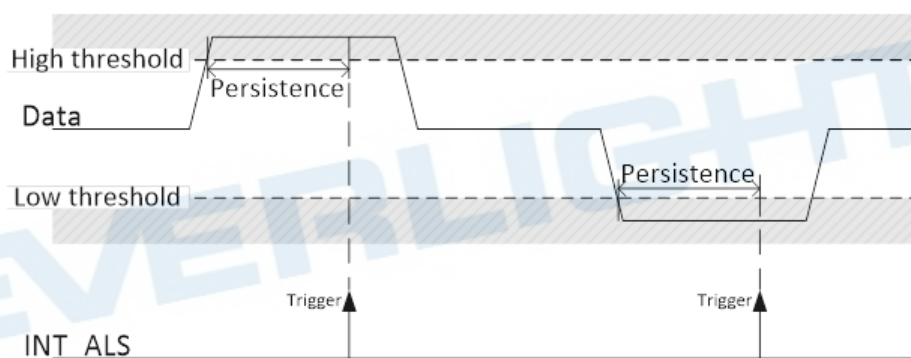
## ALS Interrupt Algorithm

Correlative register:

- The ALS Interrupt (**INT\_ALS**, register 0x02, bit0).
- The ALS Persistence (**PRS\_ALS**, register 0x0B, bit0 to bit3),
- The ALS Data (**CH0\_DATA** and **CH1\_DATA**, register 0x1C to 0x1F),
- The ALS Low Threshold (**ALS\_THRES\_L**, register 0x0C to 0x0D),
- The ALS High Threshold (**ALS\_THRES\_H**, register 0x0E to 0x0F).

**INT\_ALS** triggered condition:

1. Rule of active interrupt: **DATA** > **ALS\_THRES\_H** or **DATA** < **ALS\_THRES\_L**.
2. If the **DATA** meets the rule, the **interrupt** count increases one.  
If the **DATA** fails in the rule, the interrupt count will be clear.
3. When the **interrupt** count equal to **PRS\_ALS setting**, **INT\_ALS** will be triggered and reset the interrupt counter.
4. If **PRS\_ALS** is set to zero, **threshold** will be ignored and **DATA** will meets the active interrupt rule forcibly.



## WAIT\_TIME

| 0x03 | WAIT_TIME, waiting time (Default = 0x00) |   |   |   |   |   |   |   |
|------|------------------------------------------|---|---|---|---|---|---|---|
| BIT  | 7                                        | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R/W  | WTIME                                    |   |   |   |   |   |   |   |

**WTIME**: This register controls the time unit of waiting state which is inserted between any two measurements. It is 5ms per time unit.

0x00: 1 time unit.

0x01: 2 time units

.....

0xFF: 256 time units

## ALS\_GAIN

| 0x04 | ALS_GAIN, ALS analog gain (Default = 0x00) |   |   |   |   |         |   |   |
|------|--------------------------------------------|---|---|---|---|---------|---|---|
| BIT  | 7                                          | 6 | 5 | 4 | 3 | 2       | 1 | 0 |
| R/W  | 0                                          | 0 | 0 | 0 | 0 | PGA_ALS |   |   |

**PGA\_ALS** : ALS sensing gain.

- 0x0: x1 (default)
- 0x1: x4
- 0x2: x8
- 0x3: x32
- 0x4: x96
- 0x5, 0x6, 0x7: NA

## ALS\_TIME

| 0x05 | ALS_TIME, ALS integrated time (Default = 0x00) |   |   |   |   |   |   |   |
|------|------------------------------------------------|---|---|---|---|---|---|---|
| BIT  | 7                                              | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R/W  | ALSCONV                                        |   |   |   |   |   |   |   |

**ALSCONV** : This register controls the integrated time of AD converter at ALS mode ( $T_{ALS}$ ), and the resolution of output data (CH0\_DATA, CH1\_DATA).

- 0x00: The maximum count of **output data is** 1023,  $T_{ALS} = 5.513\text{ms}$  (default)
- 0x01: The maximum count of **output data is** 2047,  $T_{ALS} = 8.138\text{ms}$
- .....
- 0xff: The maximum count of **output data is** 65535,  $T_{ALS} = 674.888\text{ms}$

The maximum count of **output data is** minimum of  $[1024 \times (\text{ALSCONV} + 1) - 1, 65535]$ .

The conversion time of ALS function ( $T_{ALS}$ ) is decided by **ALSCONV**.

$$T_{ALS} = 2.888 + 2.625 \times (\text{ALSCONV} + 1) \quad (\text{ms})$$

## PERSISTENCE

| 0x0B | PERSISTENCE, ALS persistence setting (Default = 0x11) |   |   |   |         |   |   |   |
|------|-------------------------------------------------------|---|---|---|---------|---|---|---|
| BIT  | 7                                                     | 6 | 5 | 4 | 3       | 2 | 1 | 0 |
| R/W  | 0                                                     |   |   | 1 | PRS_ALS |   |   |   |

**PRS\_ALS** : This register sets the numbers of similar consecutive ALS interrupt events before the interrupt pin is triggered.

0x0: Every ALS conversion is done.

0x1: 1 ALS interrupt event is asserted.

.....

0xf: 15 consecutive ALS interrupt events are asserted.

## ALS\_THRES\_L

| 0x0C<br>0x0D | ALS_THRES_L, ALS low interrupt threshold (Default = 0x0000) |   |   |   |   |   |   |   |
|--------------|-------------------------------------------------------------|---|---|---|---|---|---|---|
| BIT          | 7                                                           | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R/W          | ALS_THRE_LL                                                 |   |   |   |   |   |   |   |
| R/W          | ALS_THRE_LH                                                 |   |   |   |   |   |   |   |

This register sets the lower threshold value of ALS interrupt. The interrupt algorithm compares the selected ALS data and ALS threshold value.

**ALS\_THRE\_LL** : ALS lower interrupt threshold value, LSB. (Reg. 0x0C)

**ALS\_THRE\_LH** : ALS lower interrupt threshold value, MSB. (Reg. 0x0D)

## ALS\_THRES\_H

| 0x0E<br>0x0F | ALS_THRES_H, ALS high interrupt threshold (Default = 0xFFFF) |   |   |   |   |   |   |   |
|--------------|--------------------------------------------------------------|---|---|---|---|---|---|---|
| BIT          | 7                                                            | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R/W          | ALS_THRE_HL                                                  |   |   |   |   |   |   |   |
| R/W          | ALS_THRE_HH                                                  |   |   |   |   |   |   |   |

This register sets the high threshold value of ALS interrupt. The interrupt algorithm compares the selected ALS data and ALS threshold value.

**ALS\_THRE\_HL** : ALS high interrupt threshold value, LSB. (Reg. 0x0E)

**ALS\_THRE\_HH** : ALS high interrupt threshold value, MSB. (Reg. 0x0F)

## INT\_SOURCE

| 0x16 | INT_SOURCE, ALS interrupt source (Default = 0x00) |   |   |   |   |   |   |         |
|------|---------------------------------------------------|---|---|---|---|---|---|---------|
| BIT  | 7                                                 | 6 | 5 | 4 | 3 | 2 | 1 | 0       |
| R/W  | 0                                                 | 0 | 0 | 0 | 0 | 0 | 0 | INT_SRC |

**INT\_SRC :** This register sets to select the ALS data for the ALS Interrupt algorithm.

0x0: Select CH0\_DATA.

0x1: Select CH1\_DATA.

## ERROR\_FLAG

| 0x17 | ERROR_FLAG, Error flag status |   |   |   |   |   |         |         |
|------|-------------------------------|---|---|---|---|---|---------|---------|
| BIT  | 7                             | 6 | 5 | 4 | 3 | 2 | 1       | 0       |
| R/W  | 0                             | 0 | 0 | 0 | 0 | 0 | ERR_CH1 | ERR_CH0 |

This register indicates the ALS data status. If the ALS data is outside of measurable range, the corresponding error flag (ERR\_CH0, ERR\_CH1) will set to one. That also means the data is invalid.

## CH0\_DATA

| 0x1C<br>0x1D | CH0_DATA, Channel 0 output data. |   |   |   |   |   |   |   |
|--------------|----------------------------------|---|---|---|---|---|---|---|
| BIT          | 7                                | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R/W          | CH0_DATA_L                       |   |   |   |   |   |   |   |
| R/W          | CH0_DATA_H                       |   |   |   |   |   |   |   |

The channel 0 result of ALS sensor is written into CH0\_DATA when ALS conversion is done. For insuring the data in the register comes the same measurement, the high byte data will be latched when the low byte data has been accessed until the high byte data has be read.

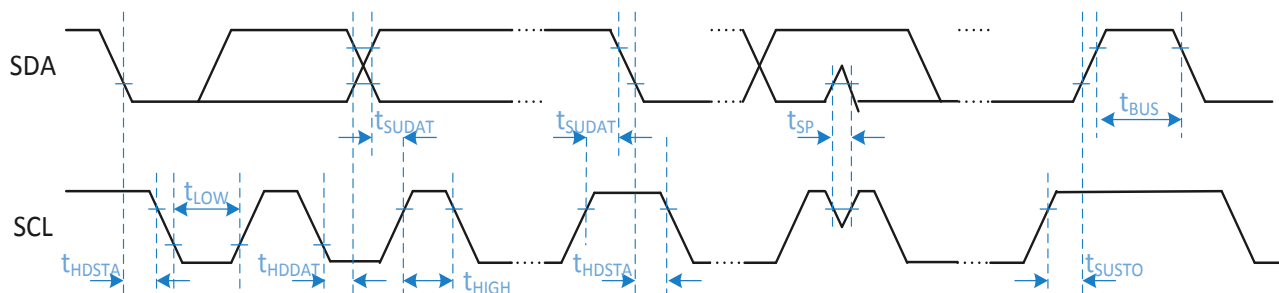
## CH1\_DATA

| 0x1E<br>0x1F | CH1_DATA, Channel 1 output data. |   |   |   |   |   |   |   |
|--------------|----------------------------------|---|---|---|---|---|---|---|
| BIT          | 7                                | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| R/W          | CH1_DATA_L                       |   |   |   |   |   |   |   |
| R/W          | CH1_DATA_H                       |   |   |   |   |   |   |   |

The channel 1 result of ALS sensor is written into CH1\_DATA when ALS conversion is done. For insuring the data in the register comes the same measurement, the high byte data will be latched when the low byte data has been accessed until the high byte data has be read.

## I<sup>2</sup>C Interface Timing Characteristics

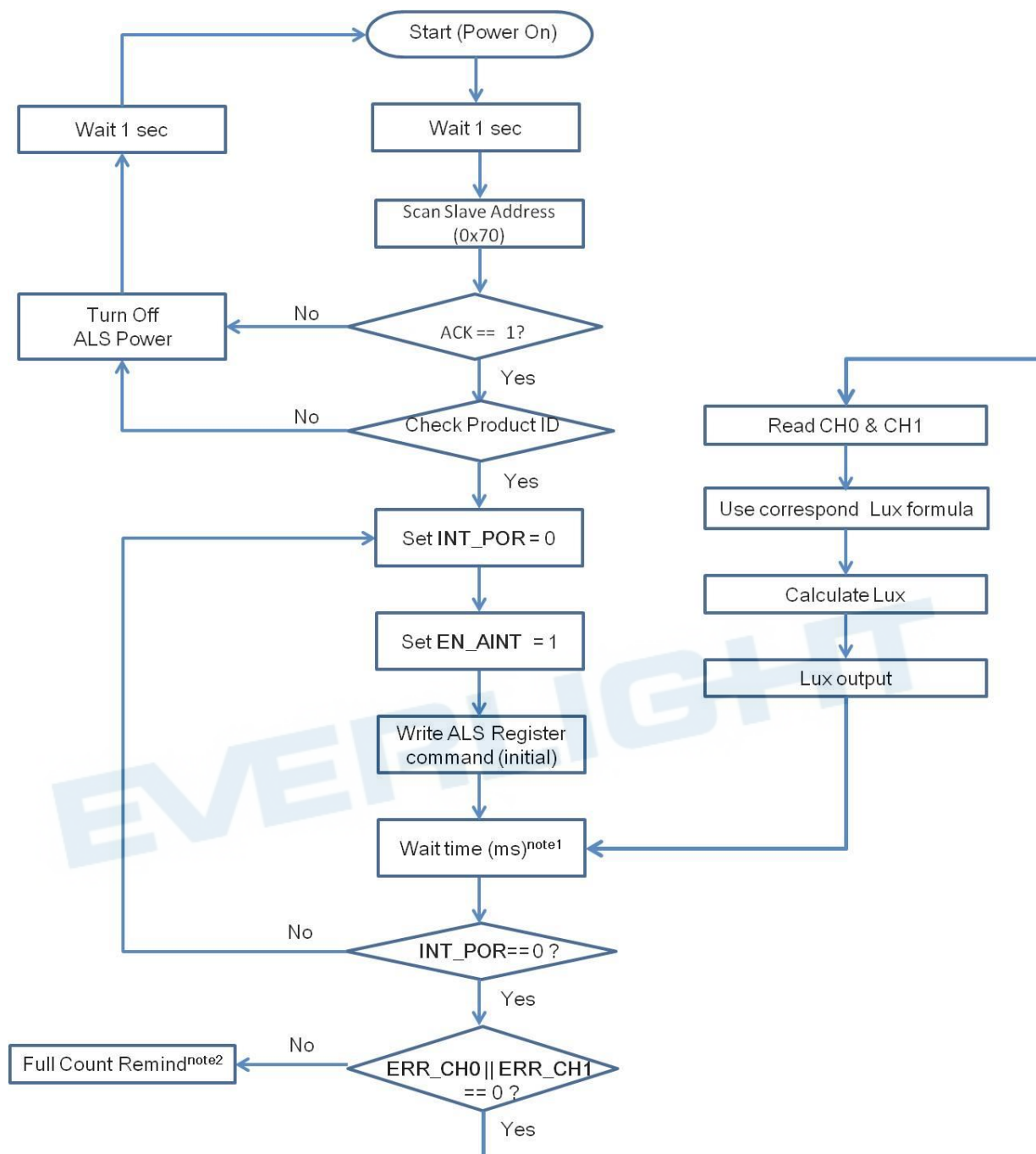
This section will describe the protocol of the I<sup>2</sup>C bus. For more details and timing diagrams please refer to the I<sup>2</sup>C specification.



| Parameter (*)                                            | Symbol      | I2C Standard Mode |      | I2C Fast Mode |      | Unit    |
|----------------------------------------------------------|-------------|-------------------|------|---------------|------|---------|
|                                                          |             | Min.              | Max. | Min.          | Max. |         |
| SCL clock frequency                                      | $f_{SCL}$   | 0                 | 100  | 0             | 400  | kHz     |
| Bus free time between STOP condition and START condition | $t_{BUS}$   | 4.7               | --   | 1.3           | --   | $\mu s$ |
| LOW period of the SCL clock                              | $t_{LOW}$   | 4.7               | --   | 1.3           | --   | $\mu s$ |
| HIGH period of the SCL clock                             | $t_{HIGH}$  | 4                 | --   | 0.6           | --   | $\mu s$ |
| Hold time (repeated) START condition                     | $t_{HDSTA}$ | 4                 | --   | 0.6           | --   | $\mu s$ |
| Set-up time (repeated) START condition                   | $t_{SUSTA}$ | 4.7               | --   | 0.6           | --   | $\mu s$ |
| Set-up time for STOP condition                           | $t_{SUSTO}$ | 4                 | --   | 0.6           | --   | $\mu s$ |
| Data hold time                                           | $t_{HDDAT}$ | 0                 | 3.45 | 0             | 0.9  | $\mu s$ |
| Data set-up time                                         | $t_{SUDAT}$ | 250               | --   | 100           | --   | $\mu s$ |
| Rise time of both SDA and SCL signals                    | $t_r$       | --                | 300  | --            | 300  | $\mu s$ |
| Fall time of both SDA and SCL signals                    | $t_f$       | --                | 1000 | --            | 300  | $\mu s$ |

(\*) All specifications are at  $V_{BUS} = 3.3V$ ,  $T_{ope}=25^{\circ}C$ , unless otherwise noted. Specified by design and characterization; not production tested.

## Basic Operation Flow Chart



Notes:

1. The wait time need to be longer than WAIT\_TIME + ALS\_TIME (ms).
2. ERR\_CH0 || ERR\_CH1 ==1 means ALS data is outside of measurable range.

Next steps can be decided by costumer, such as:

- Ignore the reminder and continue reading CH0 & CH1.
- Send an error message to MCU and wait for next command.
- Other error handling actions.

## Lux Calculating

User could calculate lux value by using the following equation (for white LED)

- If  $CH0/CH1 < 0.42$ ,  $Lux = (CH0 / PGA\_ALS) * [64 / (ALSCONV + 1)] * K1$
- If  $0.42 < CH0/CH1 < 0.61$ ,  $Lux = (CH0 / PGA\_ALS) * [64 / (ALSCONV + 1)] * K2$
- If  $CH0/CH1 > 0.61$ ,  $Lux = (CH0 / PGA\_ALS) * [64 / (ALSCONV + 1)] * K3$

Ex:

Register setting : **ALSCONV** = 0x3F, **PGA\_ALS** = 0x03, **CH0/CH1**=0.83

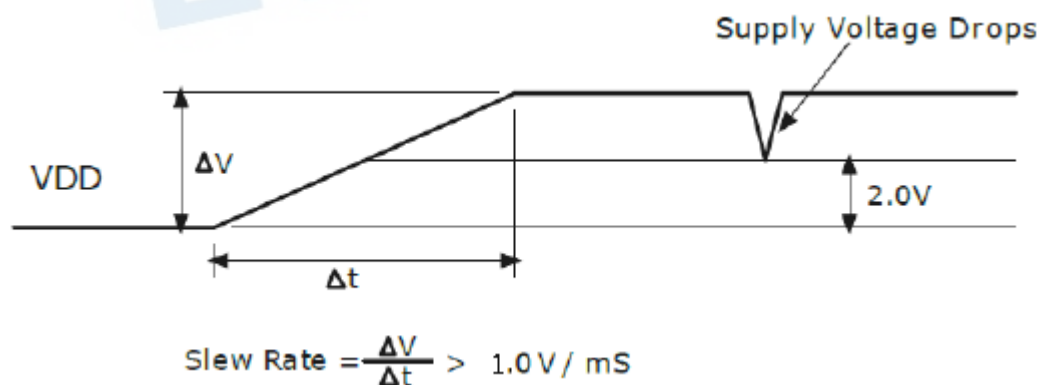
$$Lux = (CH0 / 32) * [64 / (63 + 1)] * 1.58$$

Note:

1. Recommend calibrate value : **K1 = 0.41, K2=0.57, K3 =1.58**
2. The values for **K1, K2** and **K3** shown above are only valid for the sensor component. If the sensor is placed behind an optical system (e.g. lens, cover panel etc.) the values above might not be suitable for a lux calculation. In such case the values for **K1, K2** and **K3** must be determined in the application by using a luxmeter and the sensor readings.

## Supply Voltage Drops

Upon power-up, please ensure the slew rate of VDD greater than 1.0 V/mS. After power-up , the supply voltage shall NOT drop below 2.0V. Once it happens, please switch off the power, wait more than 1 second, and then power on the device again.



**Note:**

**I<sup>2</sup>C Bus Clear**

In the unlikely event where the clock (SCL) is stuck LOW, the preferential procedure is to reset the bus using the HW reset signal if your I<sup>2</sup>C devices have HW reset inputs. If the I<sup>2</sup>C devices do not have HW reset inputs, cycle power to the devices to activate the mandatory Internal Power-On Reset (POR) circuit.

If the data line (SDA) is stuck LOW, the master should send nine clock pulses. The device that held the bus LOW should release it sometime within those nine clocks.

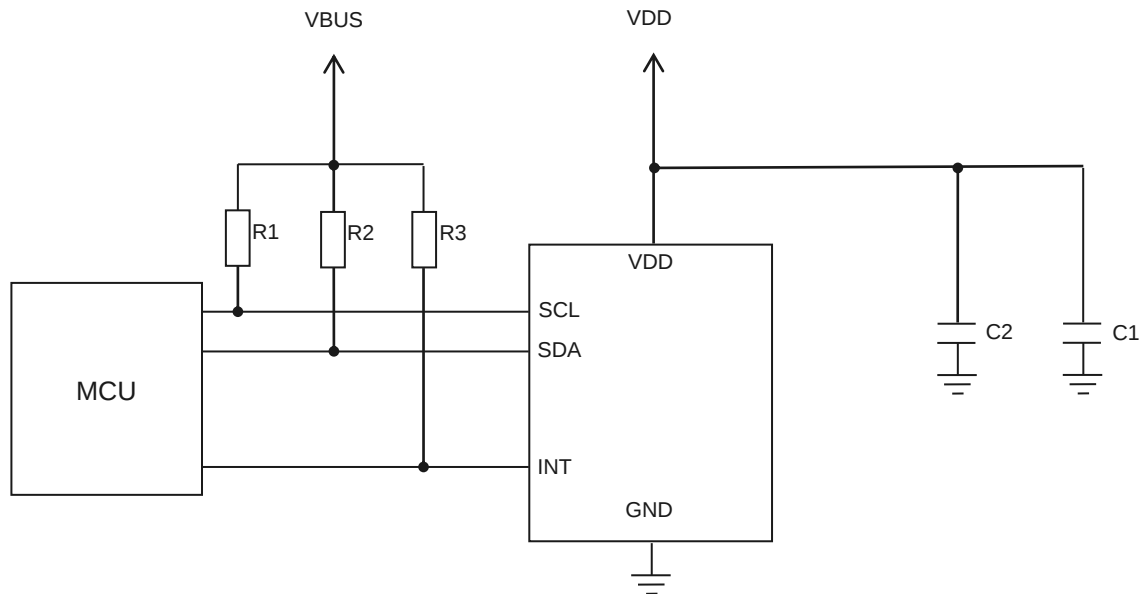
**I<sup>2</sup>C General Call Software Reset**

Following a General Call, (0000 0000), sending 0000 0110 (06h) as the second byte causes software reset. This feature is optional and not all devices will respond to this command. On receiving this 2-byte sequence, all devices designed to respond to the general call address will reset and take in the programmable part of their address.

Precautions have to be taken to ensure that a device is not pulling down the SDA or SCL line after applying the supply voltage, since these low levels would block the bus.

EVERLIGHT

## Typical Application Circuit



ALS-DPDIC17-78C/L749/TR8

The capacitors (C1, C2) are required for sensor power supply. The capacitors should be placed as close as possible to the device. The high frequency AC noises can be shunted to the ground by the capacitors. The transient current caused by digital circuit switching also can be handled by the capacitors. A typical value 0.1 / 1  $\mu$ F can be used.

The pull-up resistors (R1, R2) are required for I<sup>2</sup>C communication. At fast speed mode (400kHz/s) and VBUS = 3V, 1.0k $\Omega$  resistors can be used. The pull-up resistor (R3) is also required for the interrupt, a typical value between 10 k $\Omega$  and 100 k $\Omega$  can be used.

## Electrical and Optical Characteristics (T<sub>a</sub>=25°C)

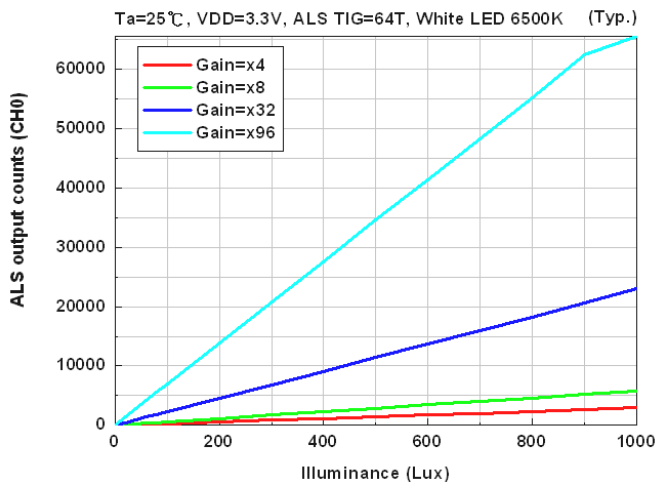


Fig.1 ALS output data vs. ALS Gain (for CH0)

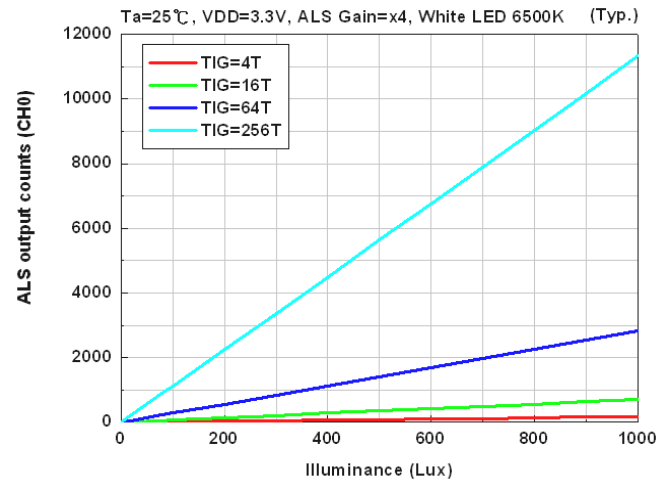


Fig.2 ALS output data vs. ADC TIG (for CH0)

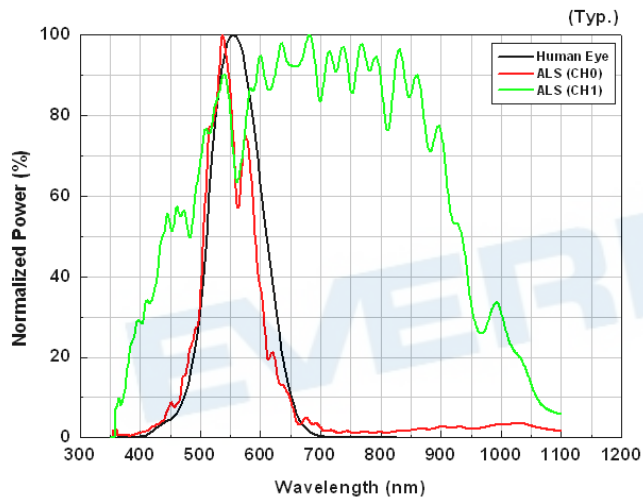


Fig.3 Spectral vs. Wavelength

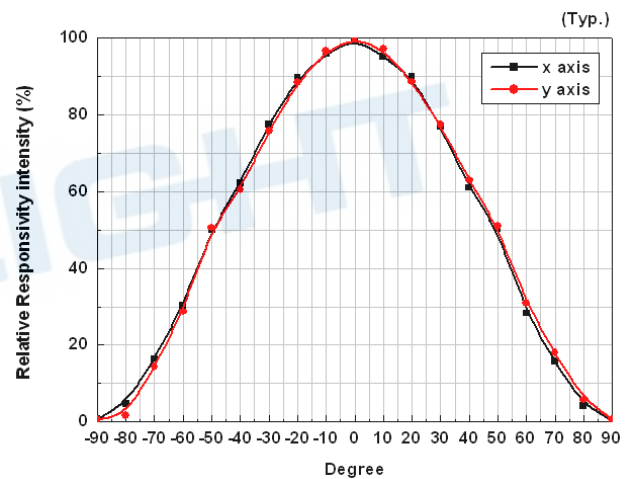
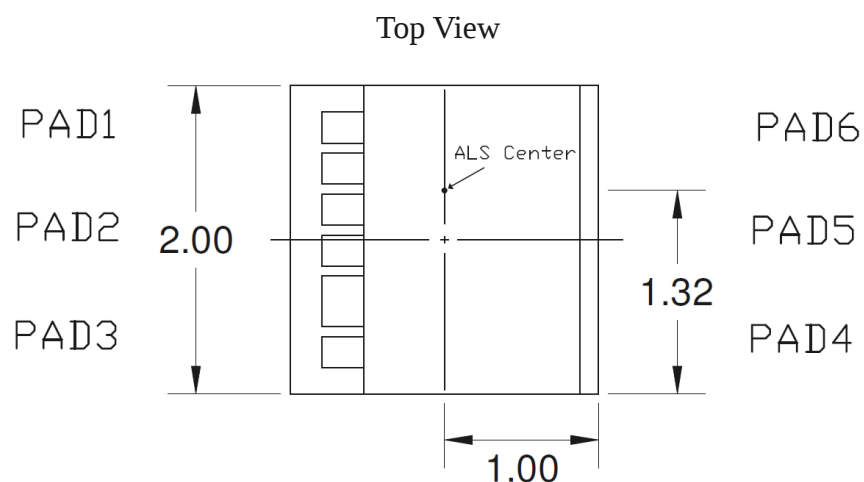


Fig.4 ALS view angle (for CH0)

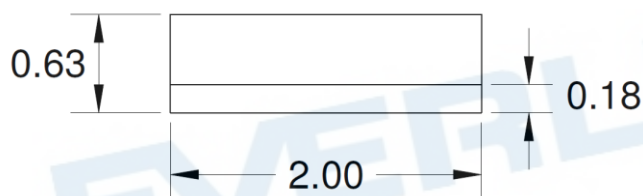
## Package Dimensions and recommended solder pad layout



Side View

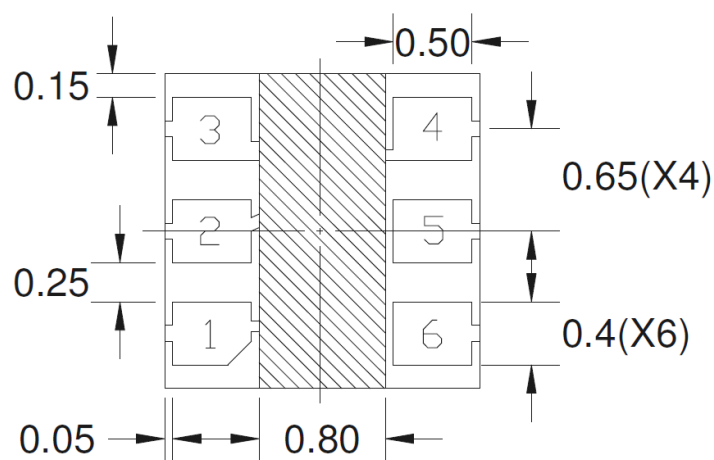


Side View

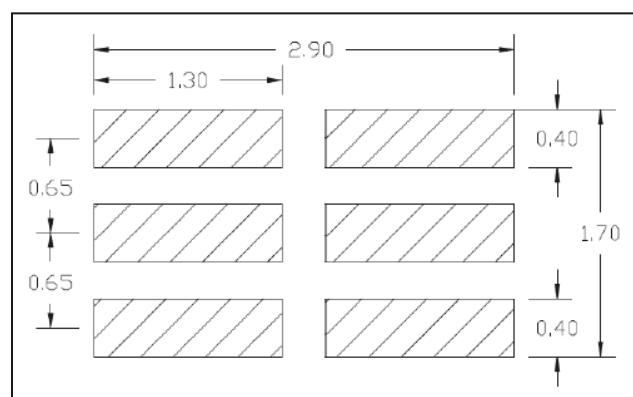


| Pad Number | Pad Name |
|------------|----------|
| 1          | VDD      |
| 2          | NC       |
| 3          | GND      |
| 4          | SCL      |
| 5          | INT      |
| 6          | SDA      |

Bottom View



Recommend soldering pad



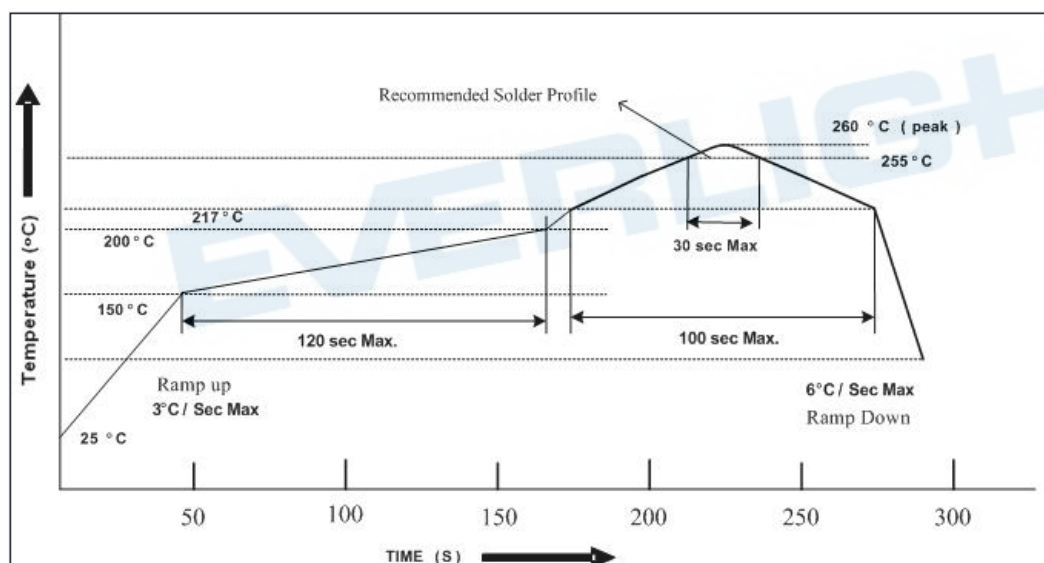
Unit: mm

Tolerances:  $\pm 0.2\text{mm}$

## Recommended method of storage

1. Do not open moisture proof bag before devices are ready to use.
2. Shelf life in sealed bag from the bag seal date: 18 months at 10°C~30°C and < 90% RH.
3. After opening the package, the devices must be stored at 10°C~30°C and ≤ 60%RH, and used within 168 hours (floor life).
4. If the moisture absorbent material (desiccant material) has faded or unopened bag has exceeded the shelf life or devices (out of bag) have exceeded the floor life, baking treatment is required.
5. If baking is required, refer to IPC/JEDEC J-STD-033 for bake procedure or recommend the following conditions:
  - 192 hours at 40°C +5/-0°C and < 5 % RH (reeled/tubed/loose units) or
  - 96 hours at 60°C ± 5°C and < 5 % RH (reeled/tubed/loose units) or
  - 24 hours at 125°C ± 5°C, not suitable for reel or tubes.

## Recommended Solder Profile



### Notice:

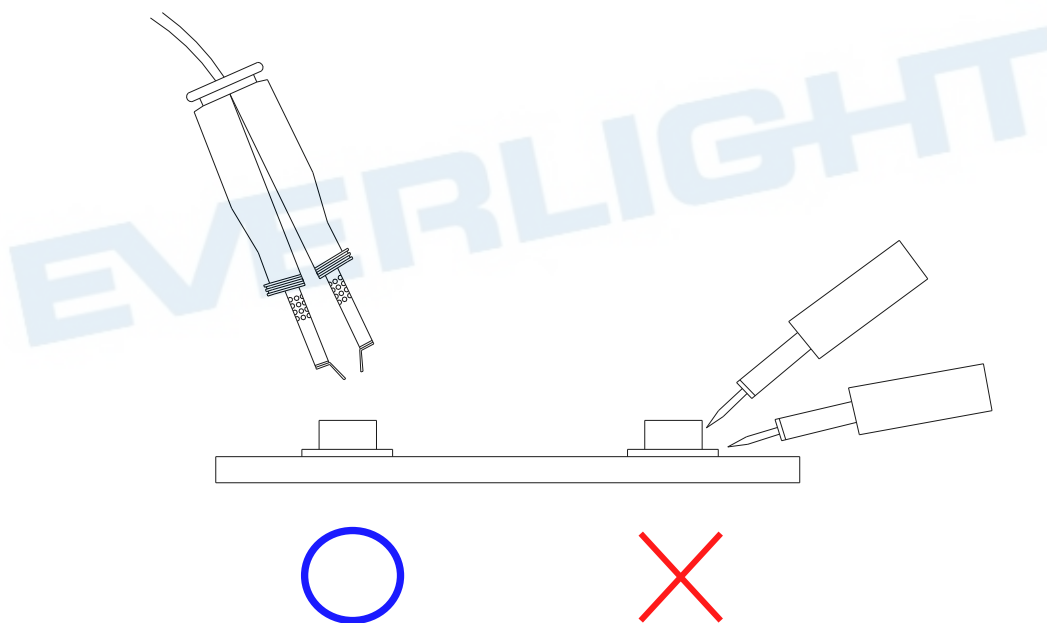
1. Reflow soldering should not be done more than two times.
2. When soldering, do not put stress on the devices during heating.
3. After soldering, do not warp the circuit board.
4. Reference: IPC/JEDEC J-STD-020D

## Soldering Iron

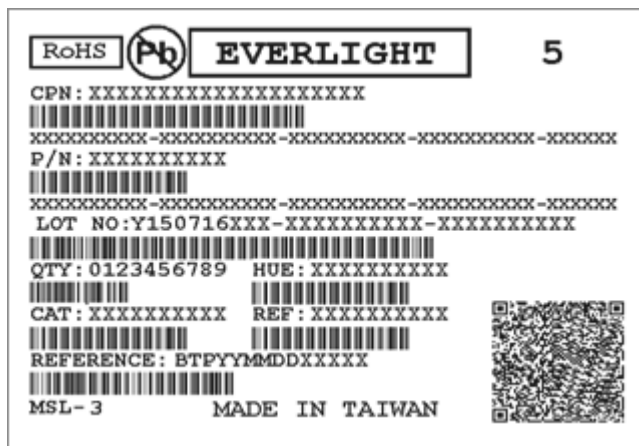
Each terminal is to go to the tip of soldering iron temperature less than 350°C for 3 seconds within once in less than the soldering iron capacity 25W. Leave two seconds and more intervals, and do soldering of each terminal. Be careful because the damage of the product is often started at the time of the hand solder.

## Repairing

Repair should not be done after the device have been soldered. When repairing is unavoidable, a double-head soldering iron should be used (as below figure). It should be confirmed beforehand whether the characteristics of the device will or will not be damaged by repairing.



## Label Explanation

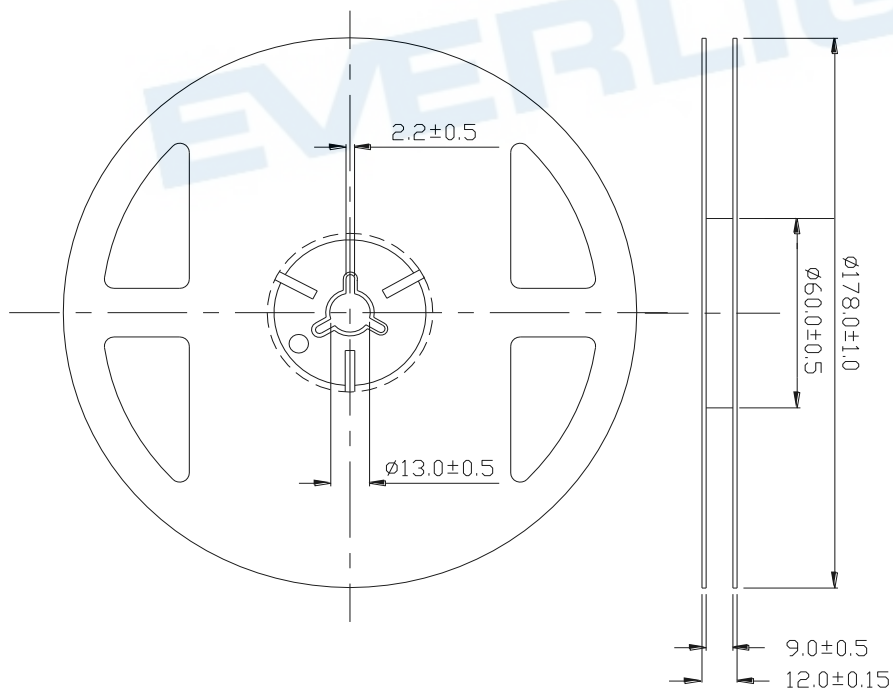


- CPN: Customer's Product Number
- P/N: Product Number
- QTY: Packing Quantity
- CAT: Luminous Intensity Rank
- HUE: Dom. Wavelength Rank
- REF: Forward Voltage Rank
- LOT No: Lot Number

## Packing Quantity Specification

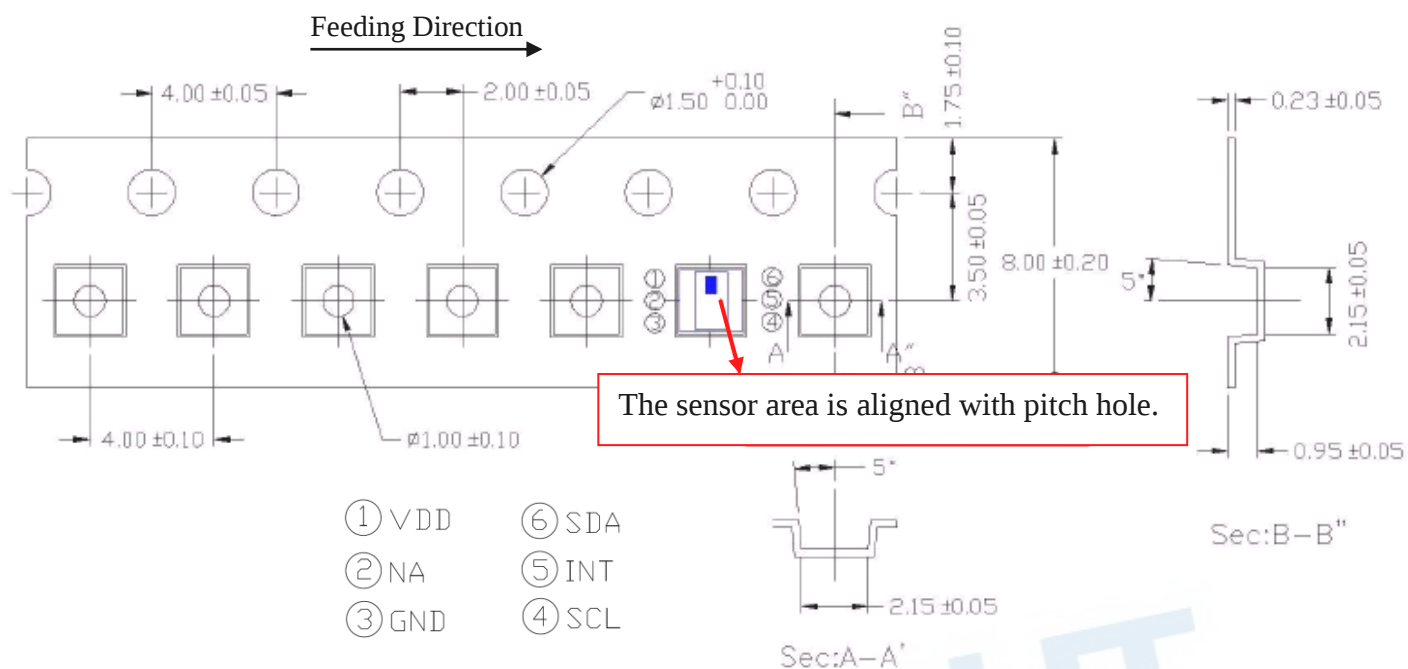
2000 PCS/ 1 Reel

## Reel Dimensions



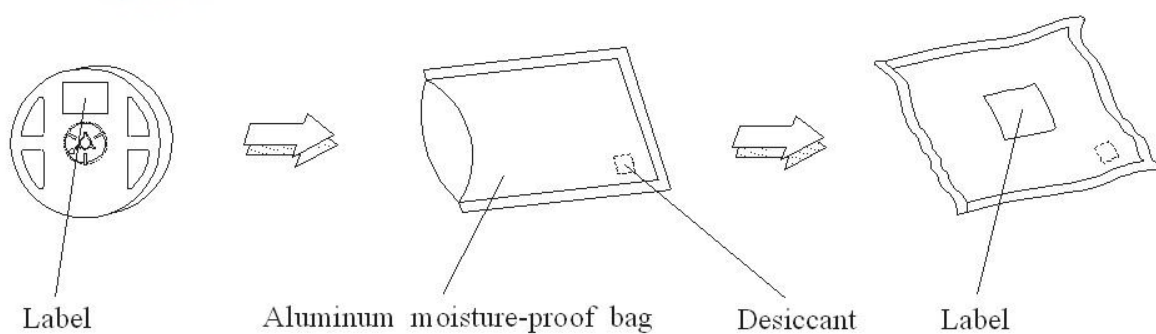
Unit: mm

## Tape Dimensions



Unit: mm

## Moisture Resistant Packing Process



## DISCLAIMER

1. EVERLIGHT reserves the right(s) on the adjustment of product materials for the specification.
2. The product meets EVERLIGHT published specification for a period of twelve (12) months from date of shipment.
3. The graphs shown in this datasheet are representing typical data only and do not show guaranteed values.
4. When using this product, please observe the absolute maximum ratings and the instructions for using outlined in these specification sheets. EVERLIGHT assumes no responsibility for any damage resulting from the use of the product which does not comply with the absolute maximum ratings and the instructions included in these specification sheets.
5. These specification sheets include materials protected under copyright of EVERLIGHT. Reproduction in any form is prohibited without obtaining EVERLIGHT's prior consent.
6. This product is not intended to be used for military, aircraft, automotive, medical, life sustaining or life saving applications or any other application which can result in human injury or death. Please contact authorized Everlight sales agent for special application request.

EVERLIGHT